

QMATH Q-LUNCH

Improving Quantum Sensing with Variational Methods

JOHANNES JAKOB MEYER, FU BERLIN & QMATH

 @jj_xyz

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A variational toolbox for quantum multi-parameter estimation

Johannes Jakob Meyer,¹ Johannes Borregaard,^{2,3} and Jens Eisert¹

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(Dated: June 11, 2020)



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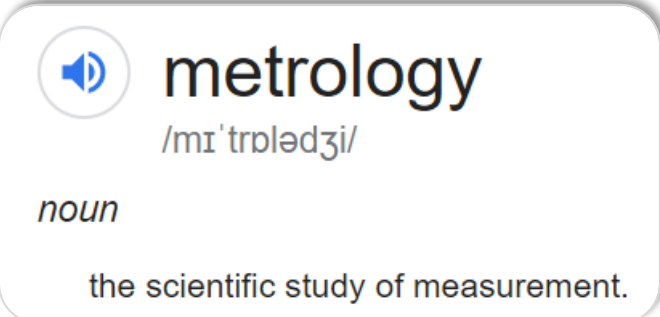
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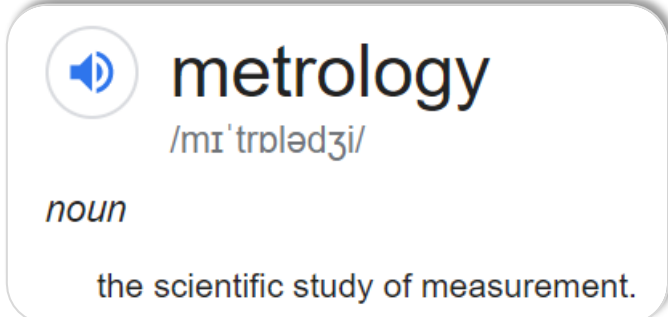



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Probe
State




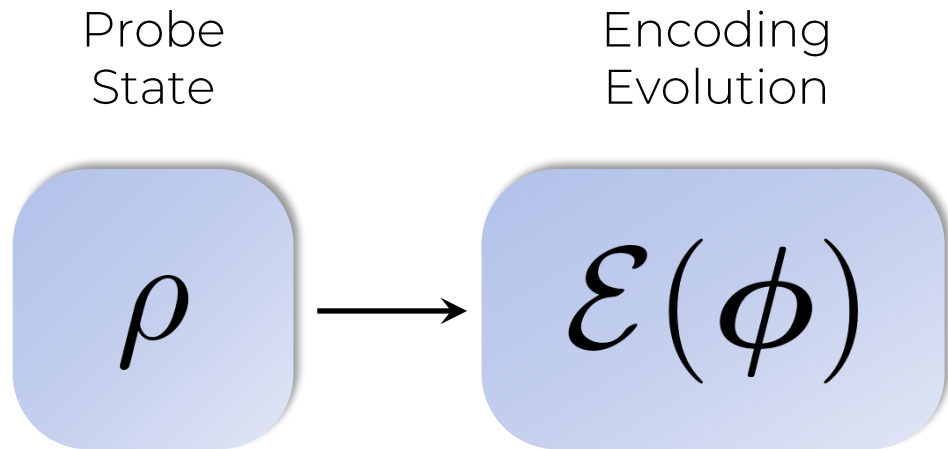
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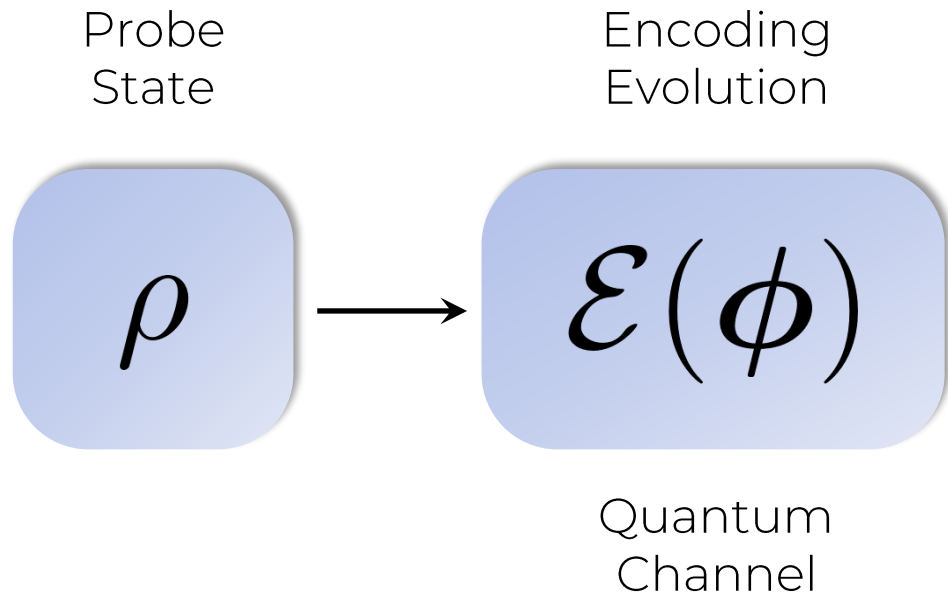


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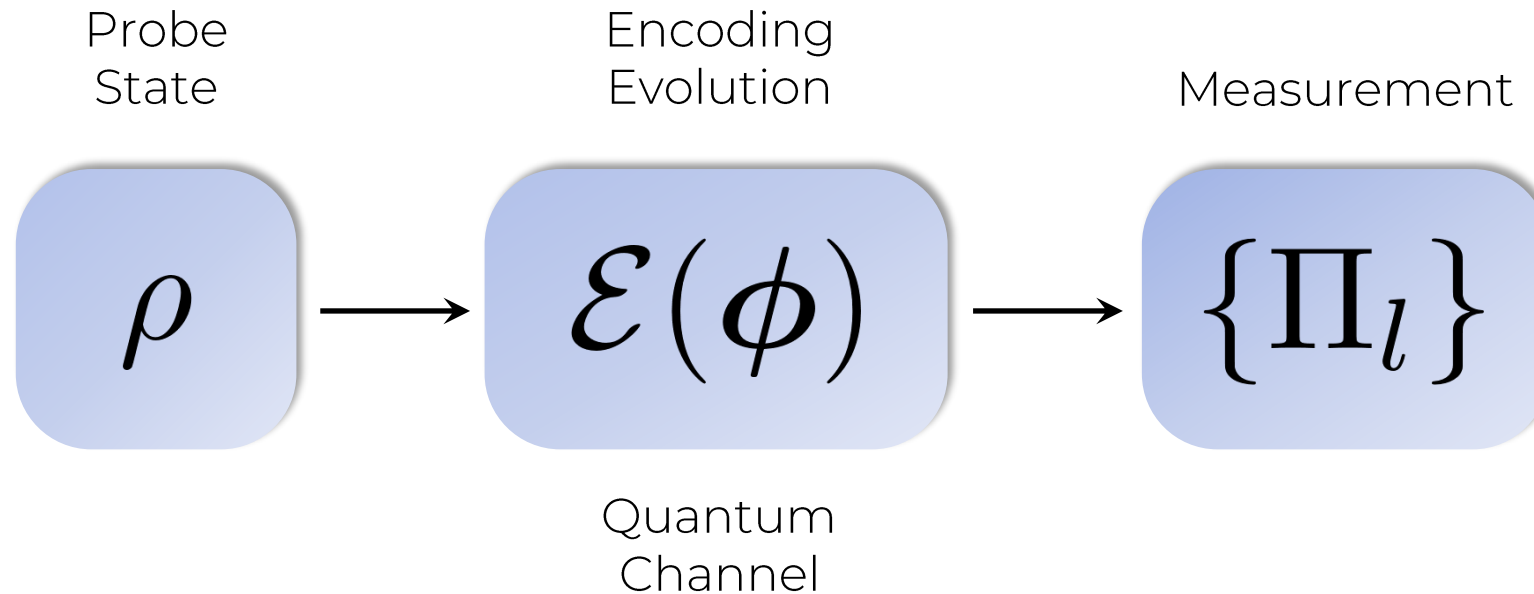


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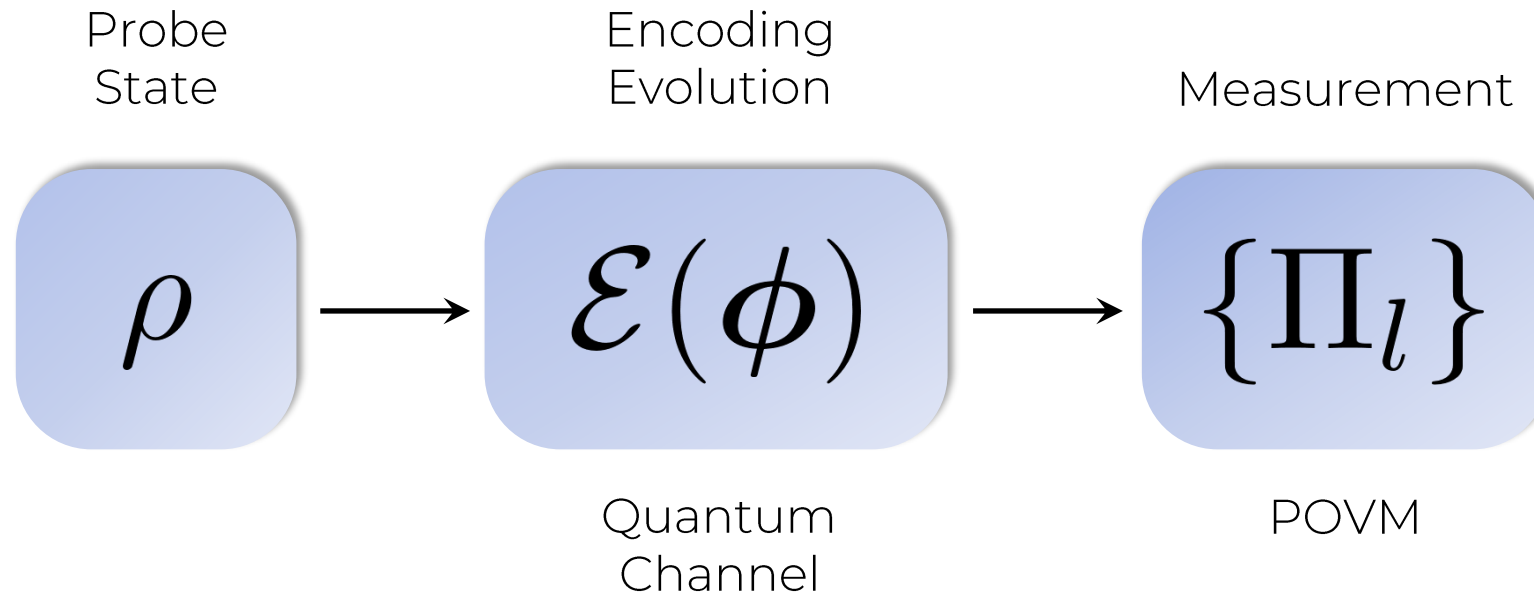


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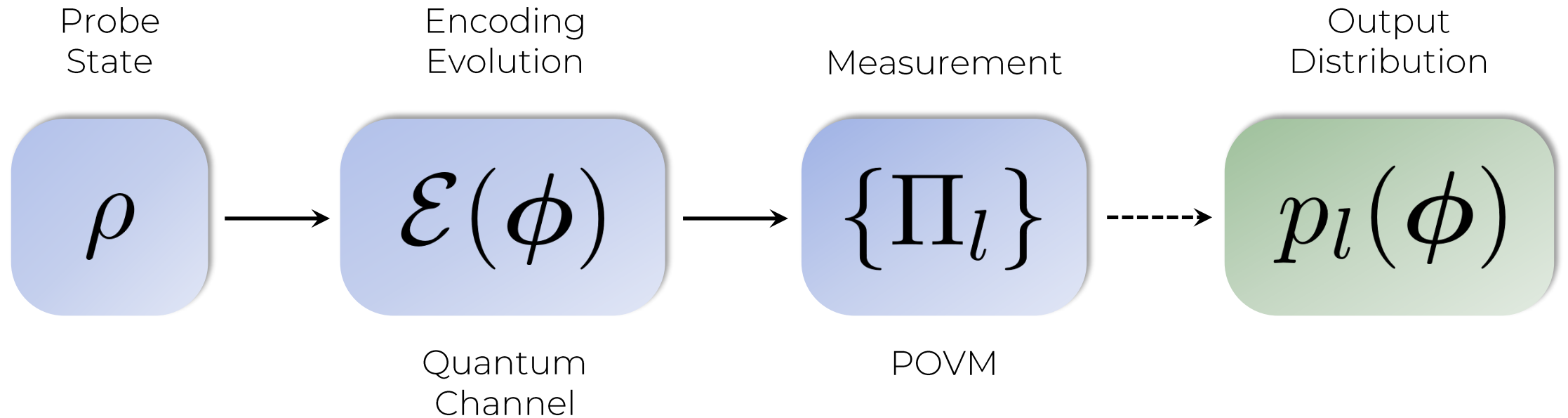
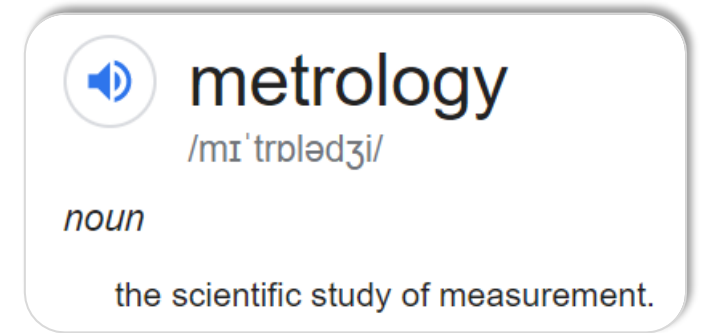
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Cramér-Rao Bound

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Task: Compute an **estimator** from samples of the output distribution

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Pr $\text{Tr}\{\text{Cov}(\hat{\varphi})\} = \text{MSE}(\hat{\varphi})$ Cramér-Rao bound

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Recap #1

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→ Classical Fisher information should be used to judge sensing quality!

Optimal Metrology

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We need to find optimal probes and measurements

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Complicated under noise and device limitations

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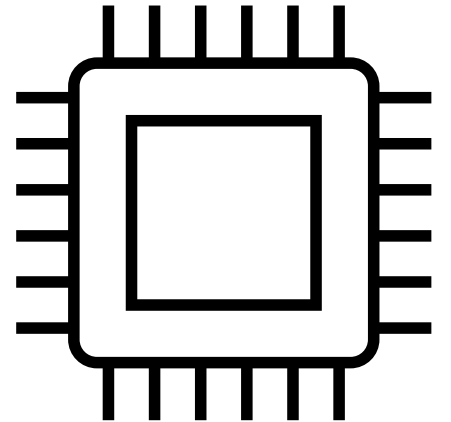
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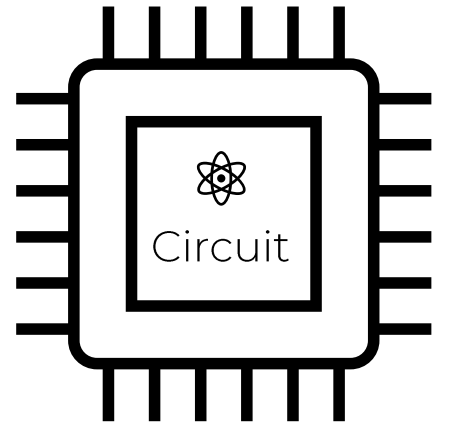


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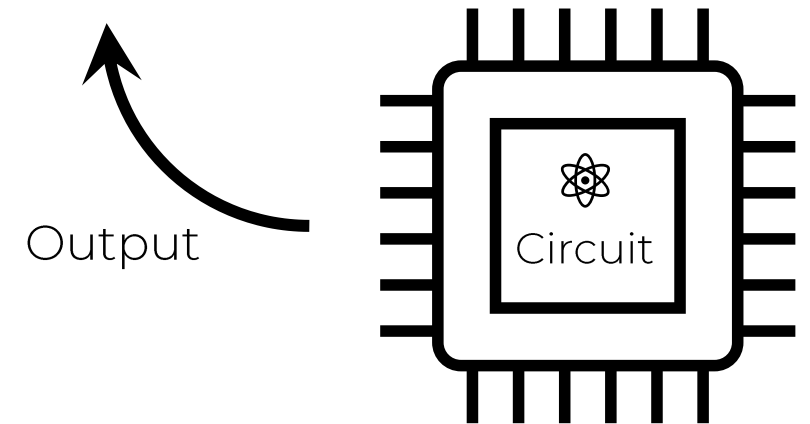


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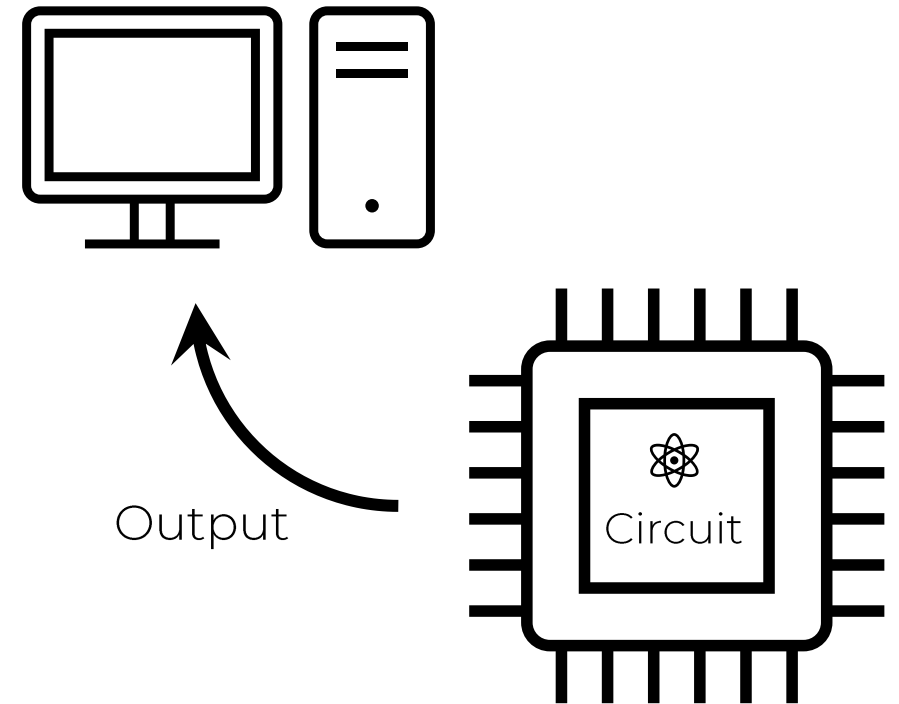


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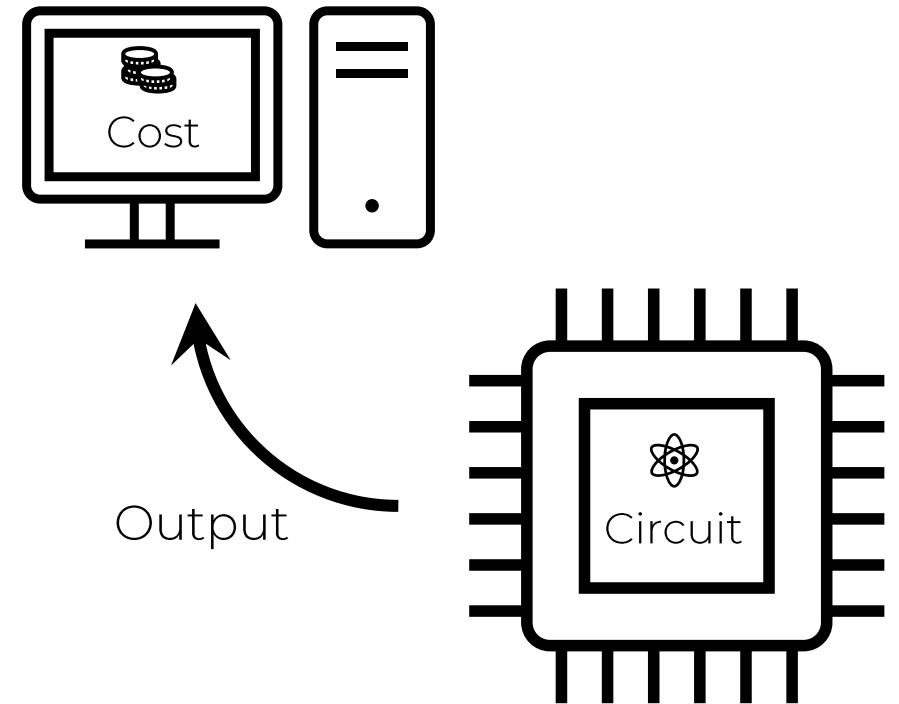


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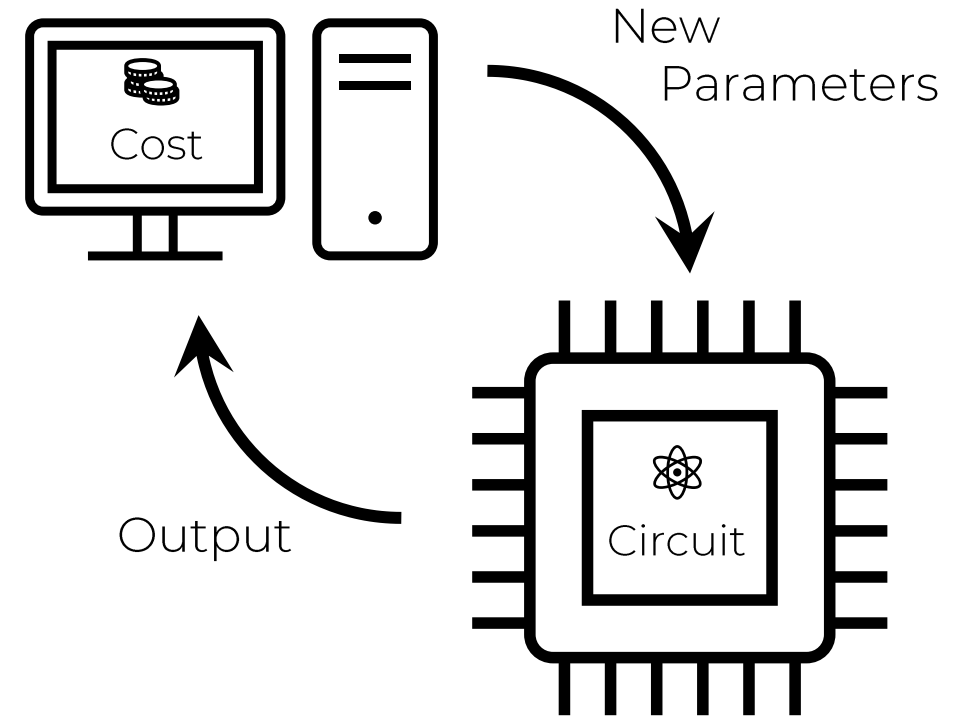


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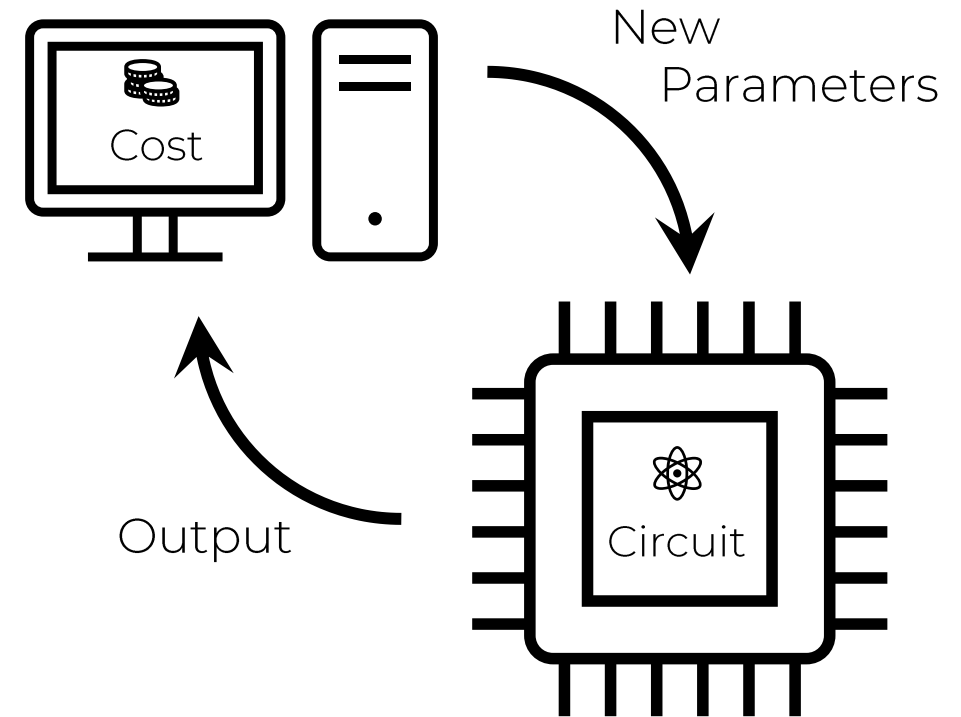
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Prior work^{1,2} focused on probes for
single-parameter metrology and surrogates
for the Quantum Fisher Information

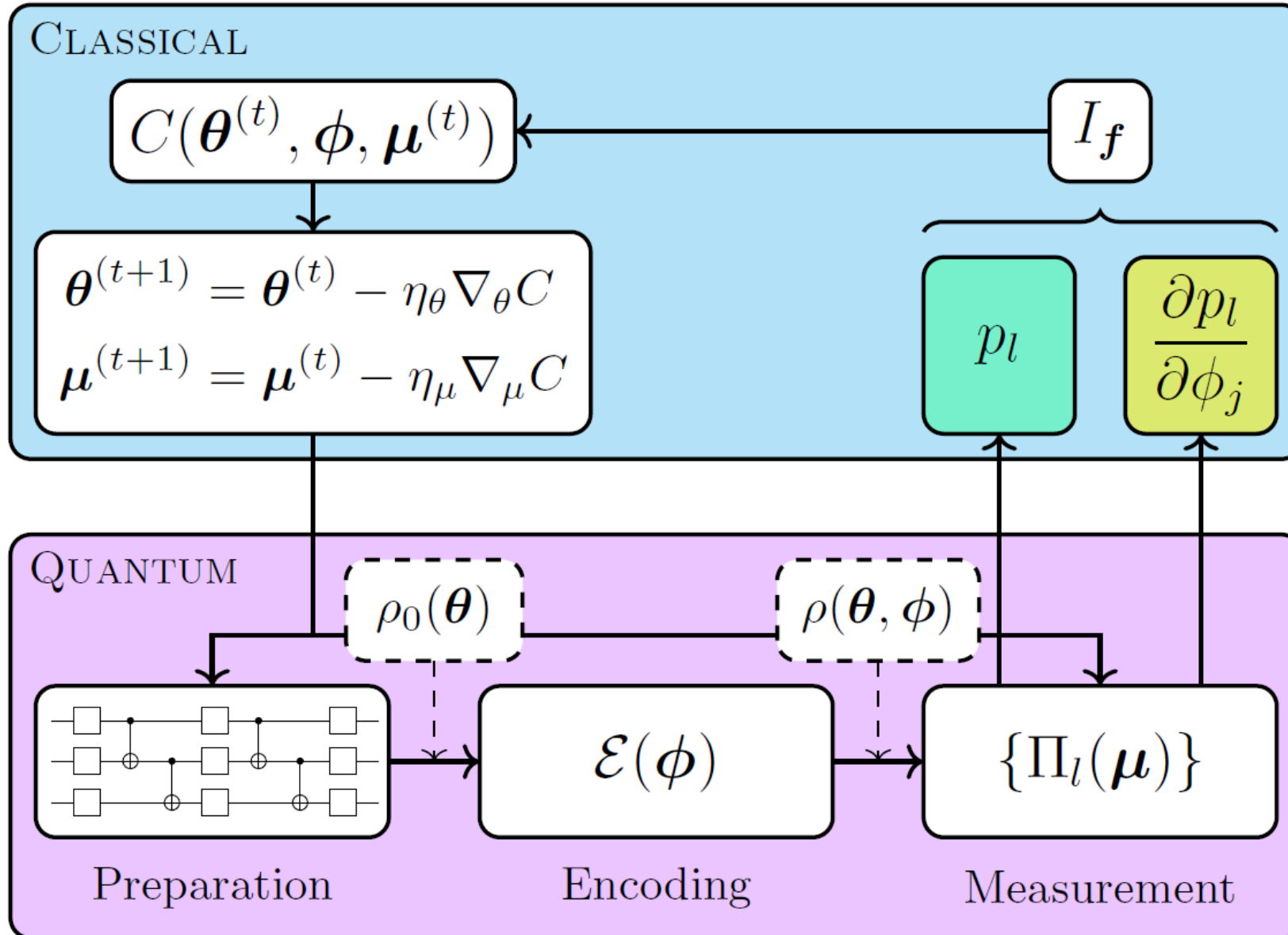


¹Kaubruegger, Raphael, et al. *Physical Review Letters* 123.26 (2019): 260505.

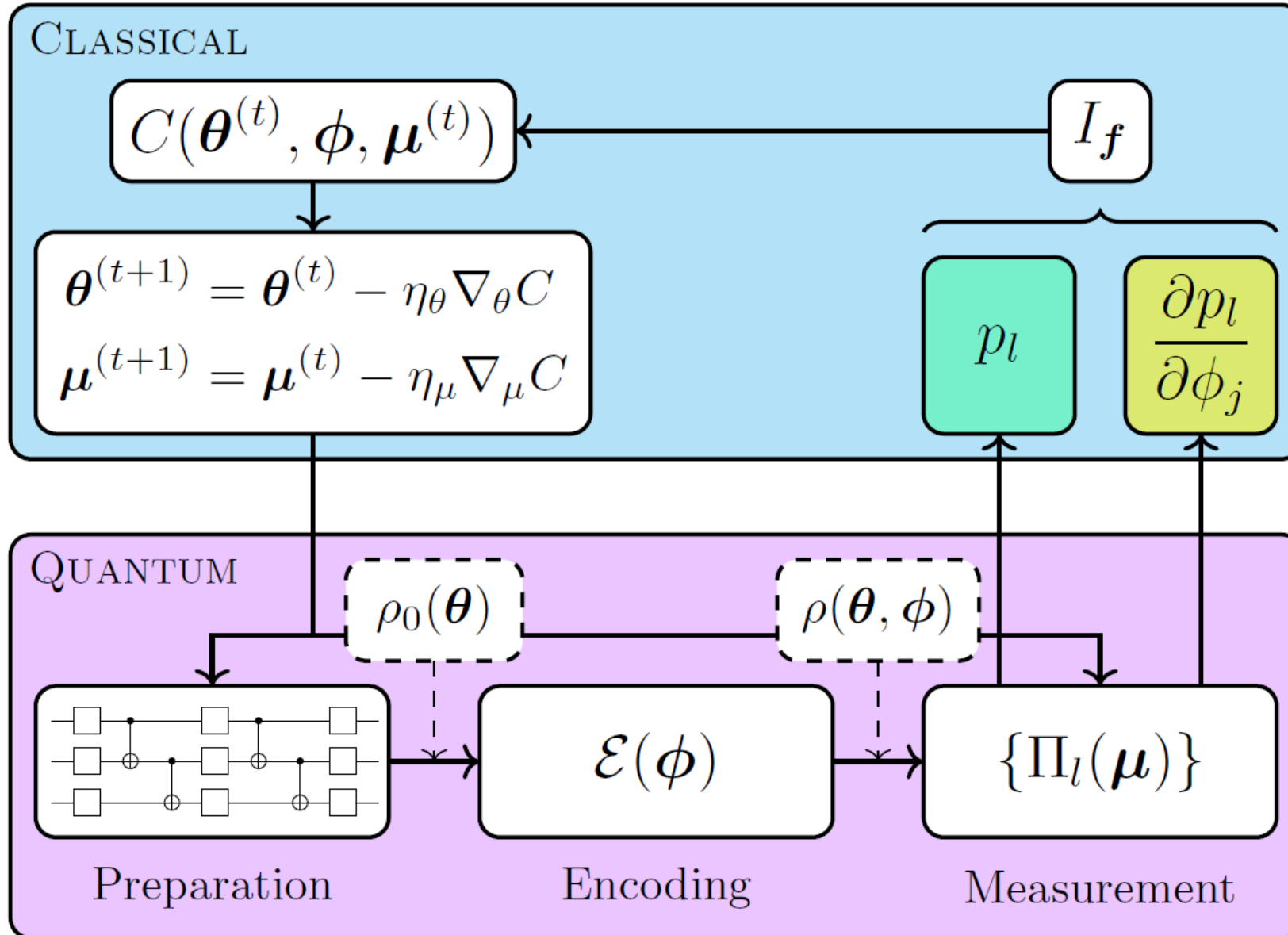
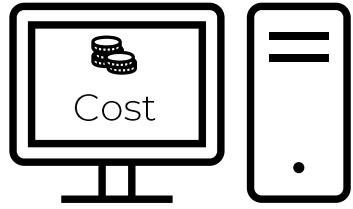
²Koczor, Bálint, et al. "Variational-State Quantum Metrology." *New Journal of Physics* (2020).

The Algorithm

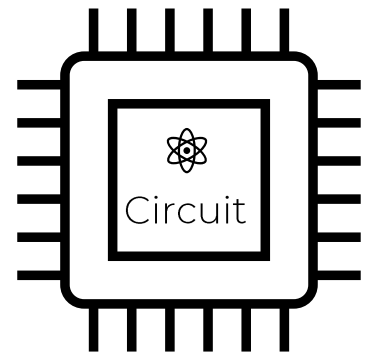
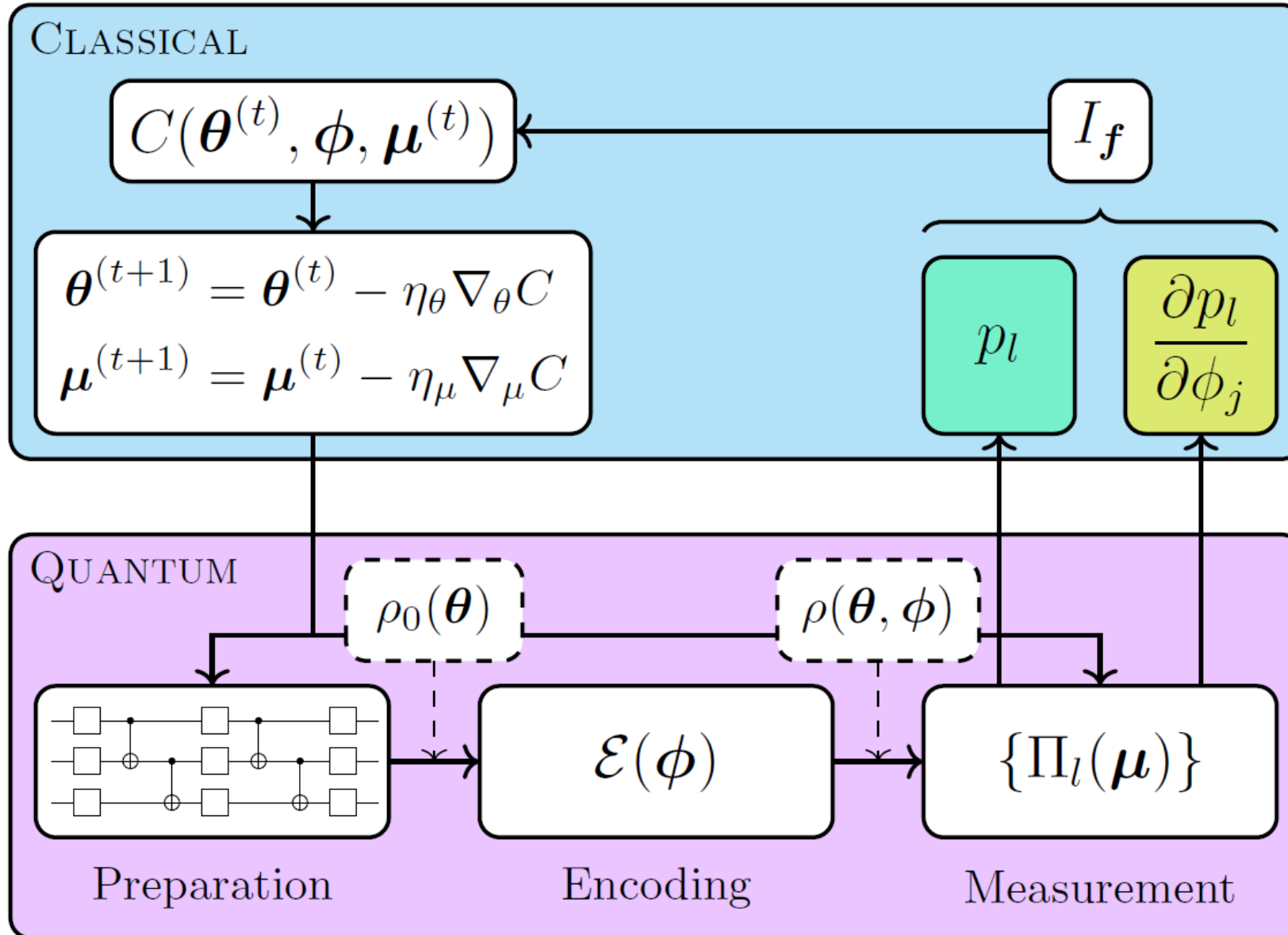
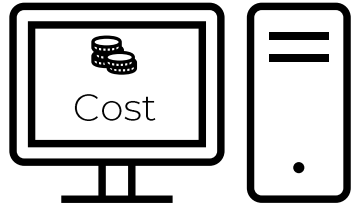
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Calculation of Fisher Information

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Fisher Information Matrix w.r.t. the physical parameters

$$[I_{\phi}]_{jk} = \sum_l \frac{1}{p_l} \frac{\partial p_l}{\partial \phi_j} \frac{\partial p_l}{\partial \phi_k}$$

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Exploit parameter-shift rule^{1,2} to calculate derivatives

$$\partial_j p_l(\phi) = \frac{1}{2} \left[p_l \left(\phi + \frac{\pi}{2} \mathbf{e}_j \right) - p_l \left(\phi - \frac{\pi}{2} \mathbf{e}_j \right) \right]$$

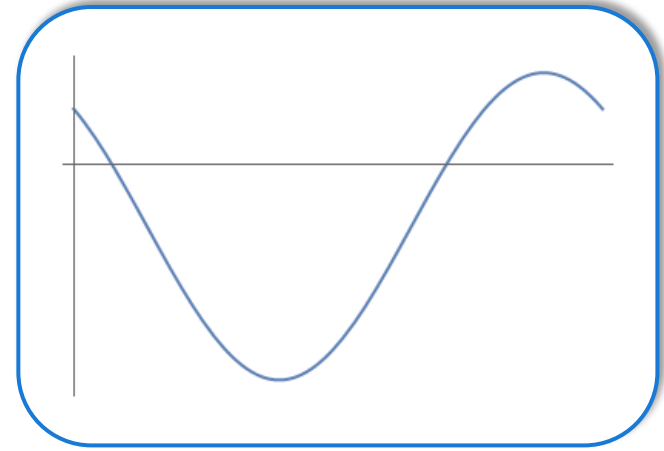
¹Schuld, Maria, et al. *Physical Review A* 99.3 (2019): 032331.

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Apply weighted trace to both sides of the CRB!

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$$\begin{aligned} \text{Tr}\{W \text{Cov}(\hat{\boldsymbol{\varphi}})\} &= \text{MSE}_W(\hat{\boldsymbol{\varphi}}) \\ &= \mathbb{E}\{\langle \hat{\boldsymbol{\varphi}} - \boldsymbol{\phi}, W(\hat{\boldsymbol{\varphi}} - \boldsymbol{\phi}) \rangle\} \end{aligned}$$

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The cost function is obtained from a weighted trace of the Cramér-Rao bound

Implementation Prerequisites

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Knowledge about the encoding process and noise sources

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Example: Unitary encoding with commuting noise process

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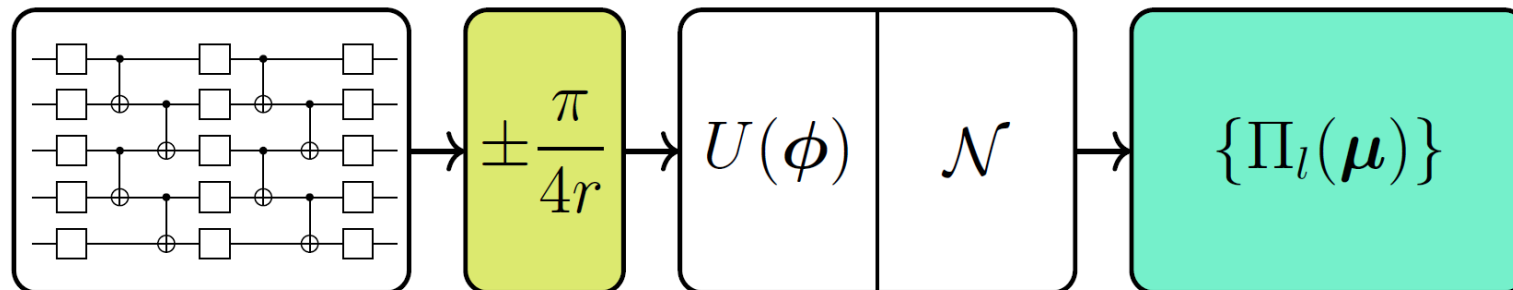
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Example: Unitary encoding with phase injection



Numerics: Ramsay Spectroscopy

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Task: Estimate the average of three phases under dephasing noise

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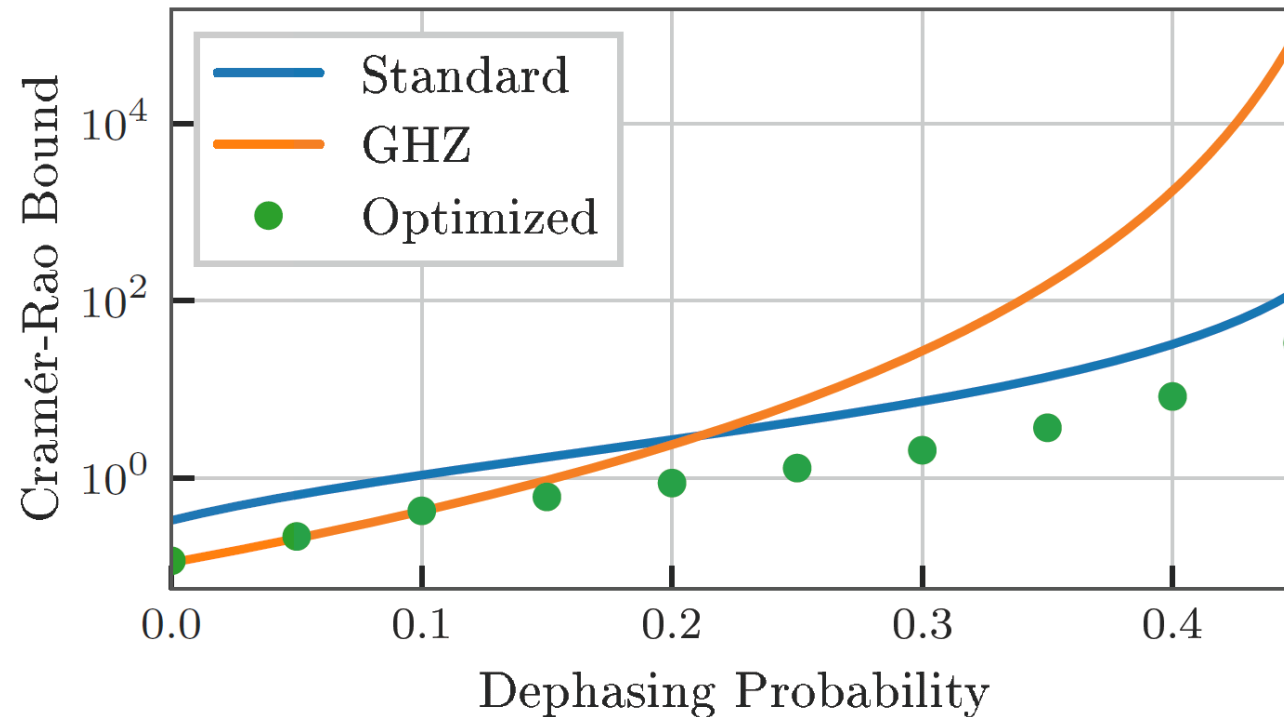
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Fixed phase parameters and varied noise level

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Numerics: NV Trilateration

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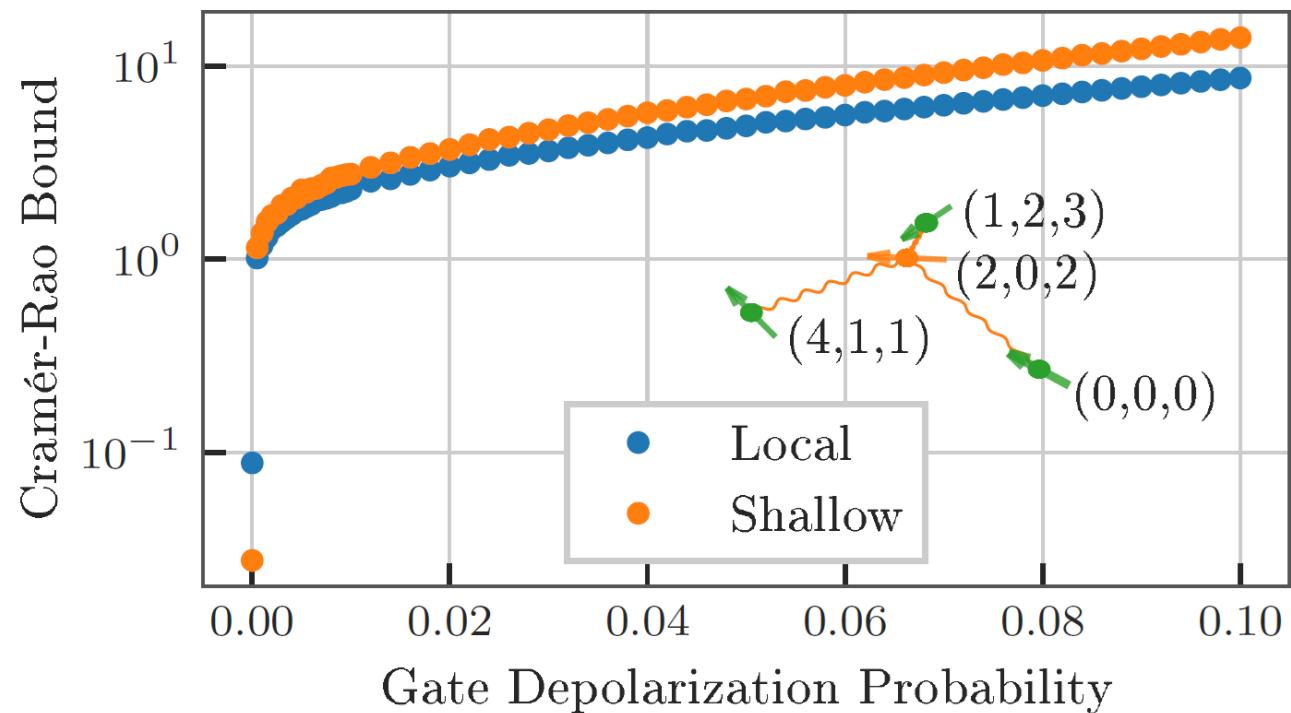
Task: Estimate the position of a spin interacting with three sensing spins

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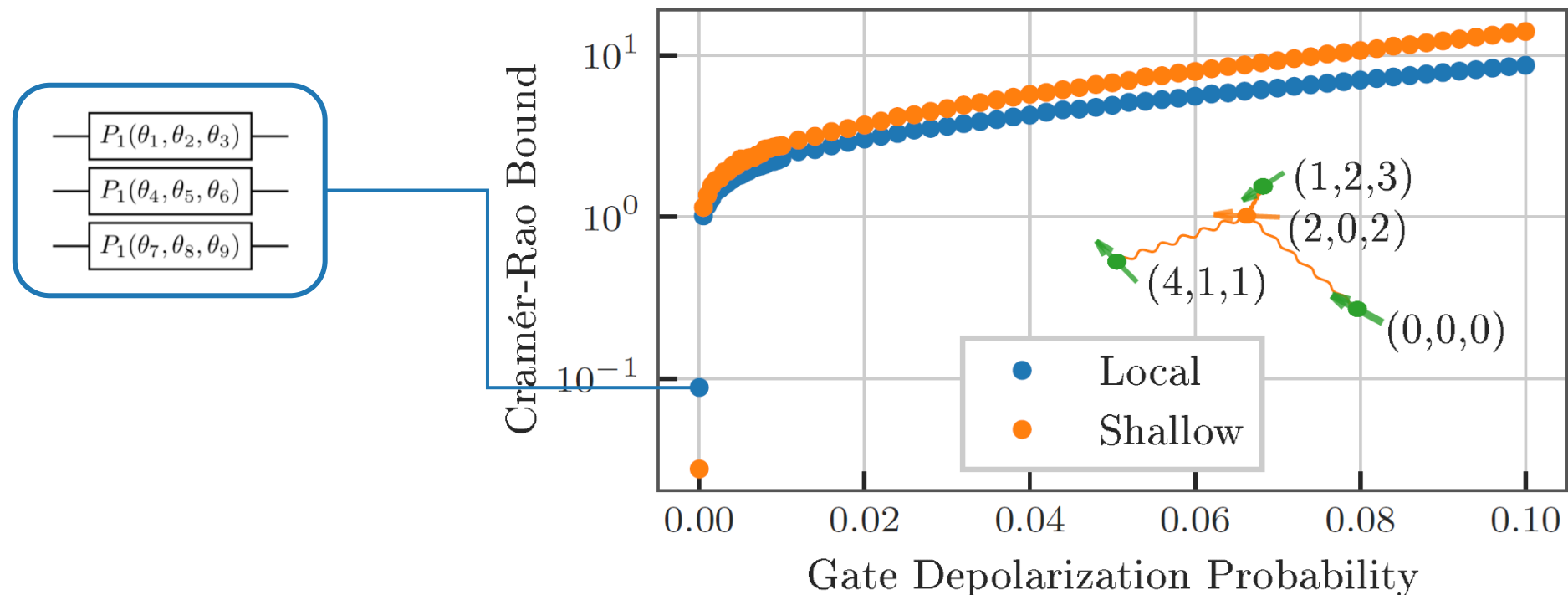
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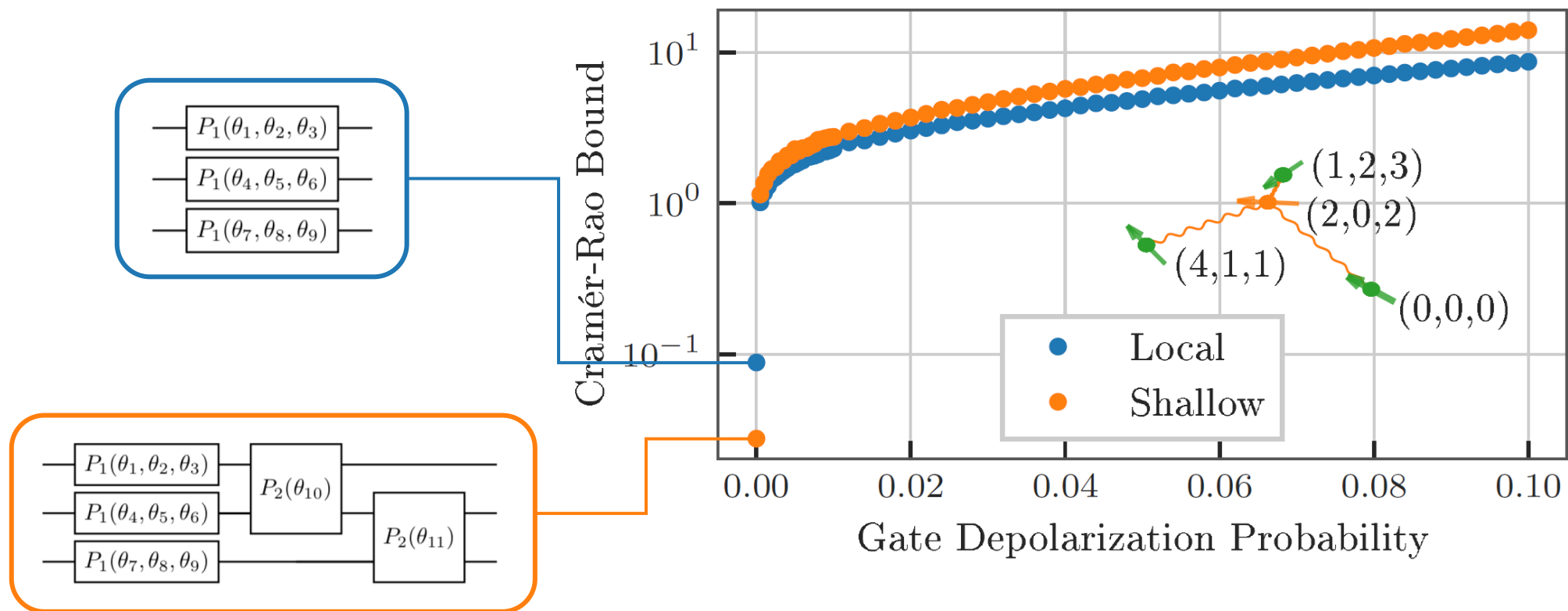
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We provide multiple extensions of the algorithm, for example including prior knowledge (Bayesian approach)

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We give details on the implementation of parameter-shift rules

The Algorithm Landscape

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■ Single Parameter

■ Multiparameter



The Algorithm Landscape

■ Single Parameter ■ Multiparameter

Kaubrügger et al.

COST FUNCTION

Spin Squeezing

STATE PREPARATION

Fixed Circuit

MEASUREMENT

Fixed



The Algorithm Landscape

■ Single Parameter ■ Multiparameter

Kaubrügger et al.

COST FUNCTION

Spin Squeezing

STATE PREPARATION

Fixed Circuit

MEASUREMENT

Fixed

Koczor et al.

COST FUNCTION

Fidelity

STATE PREPARATION

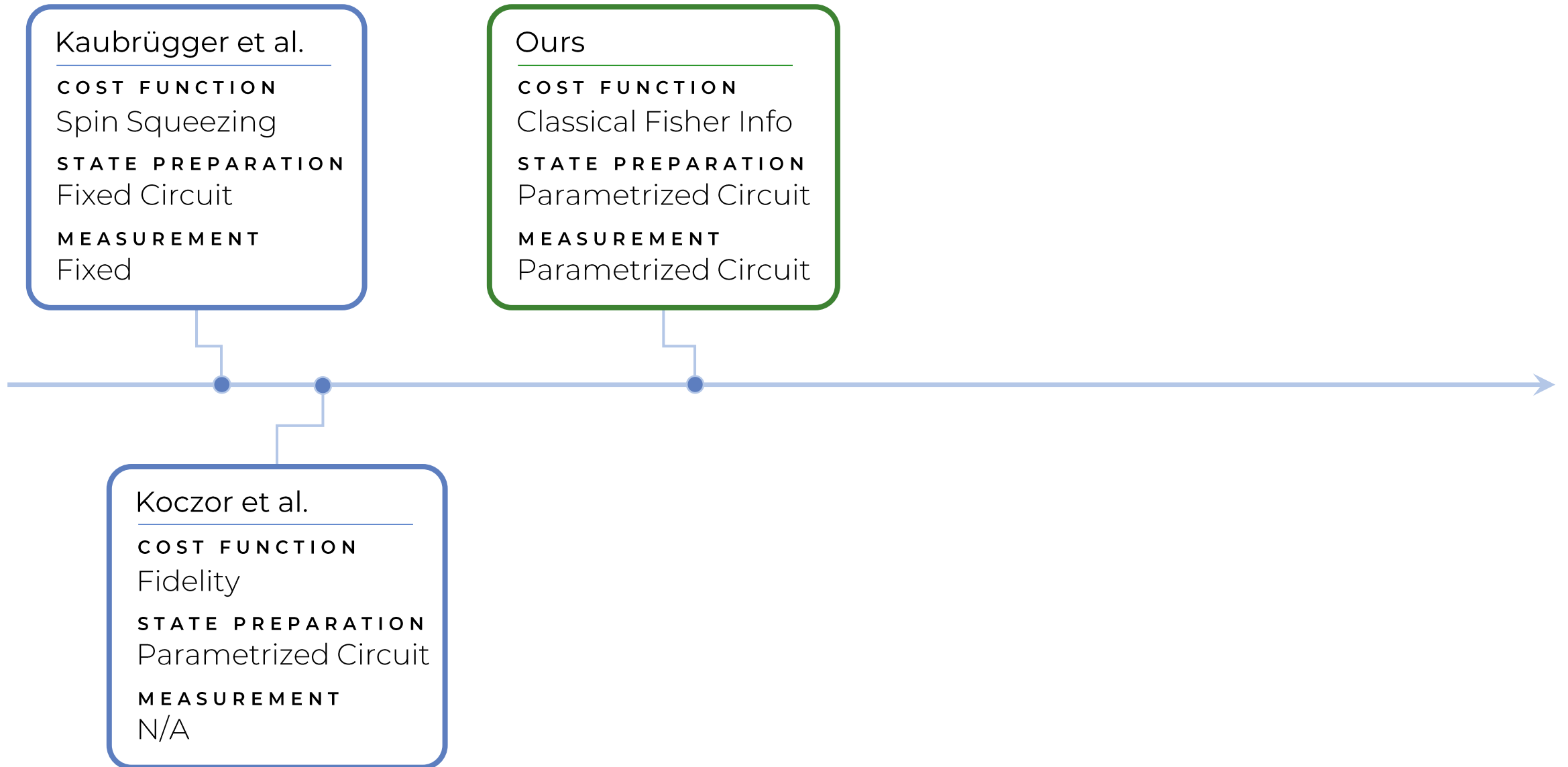
Parametrized Circuit

MEASUREMENT

N/A

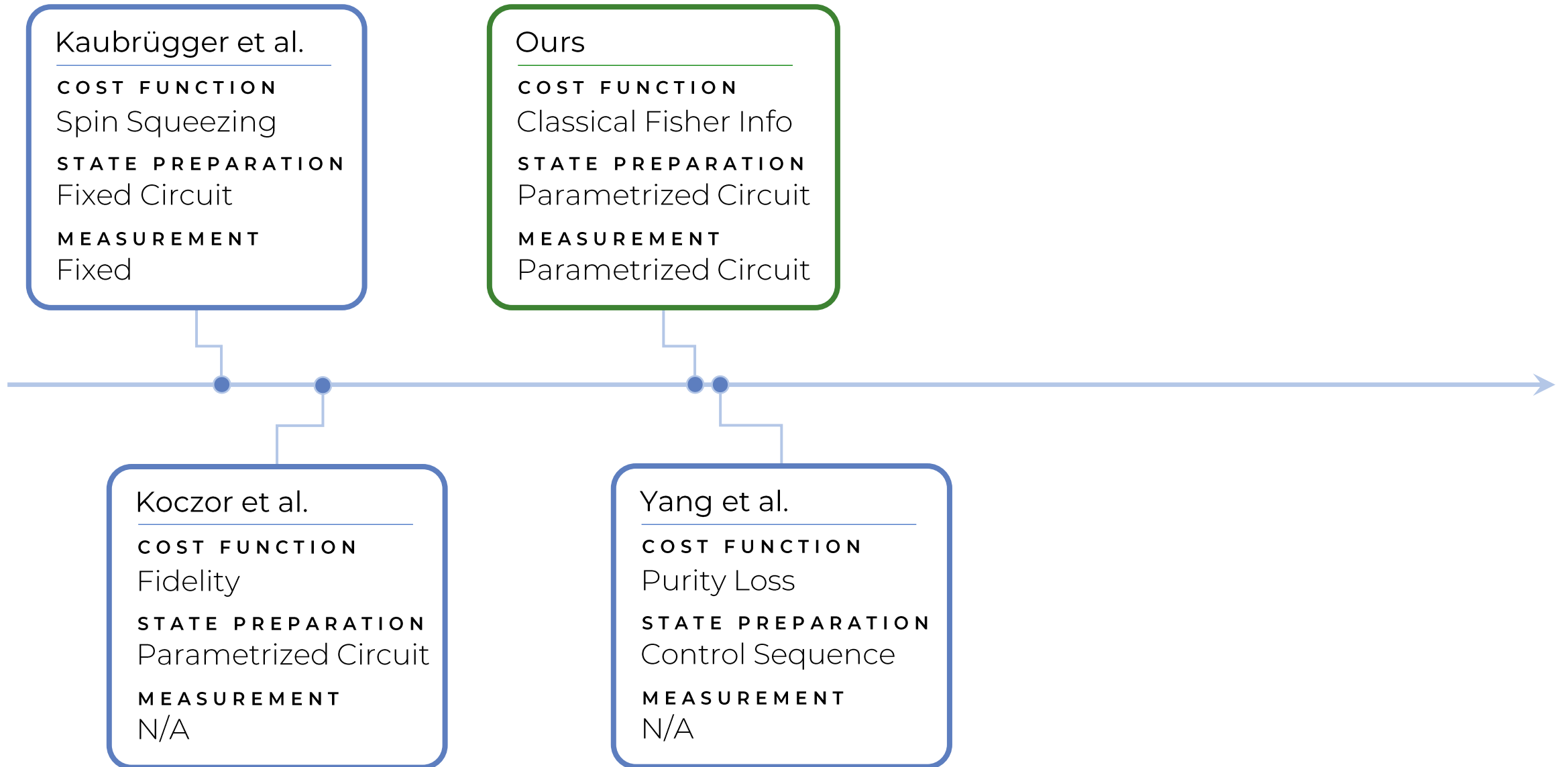
The Algorithm Landscape

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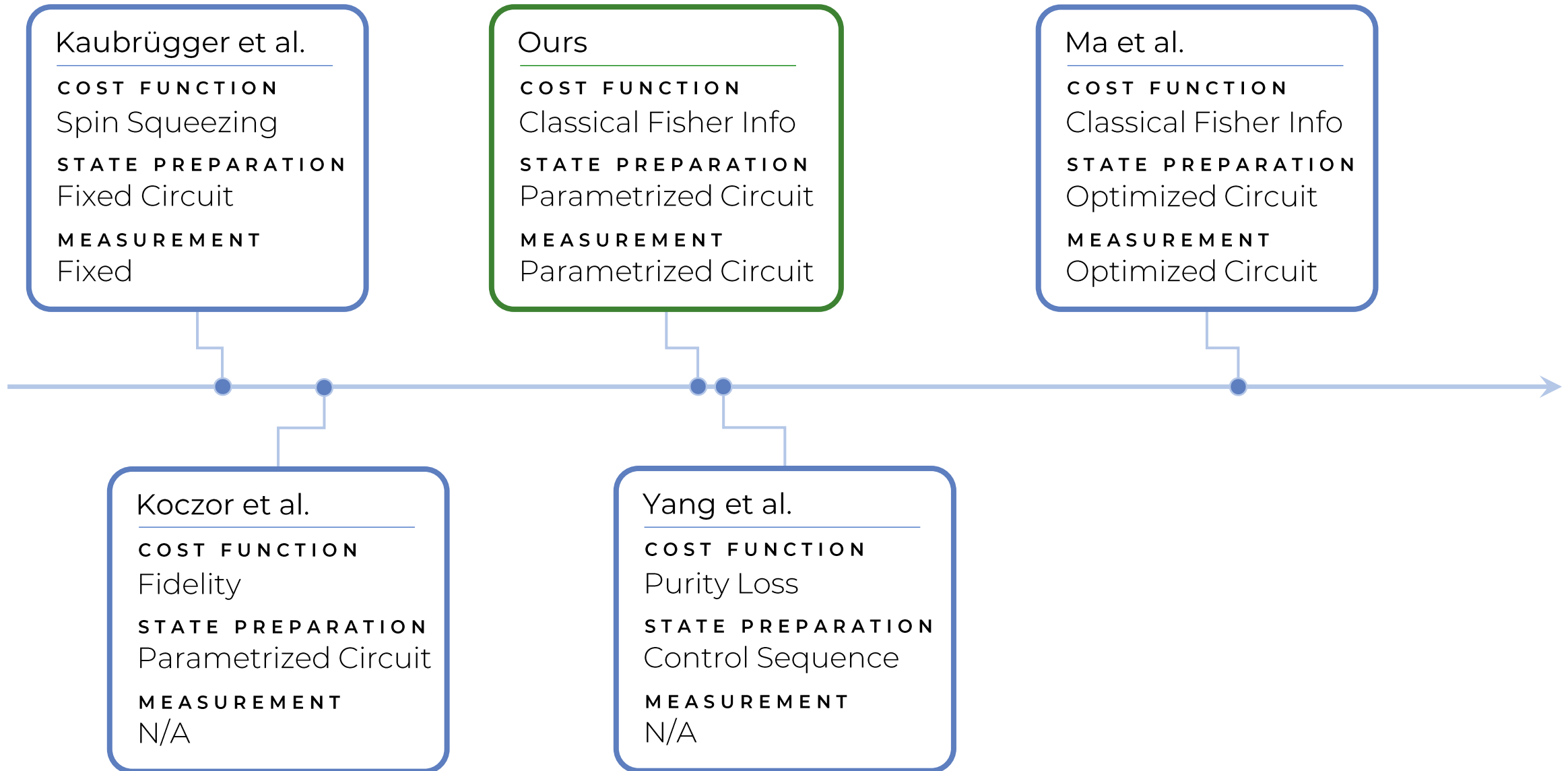
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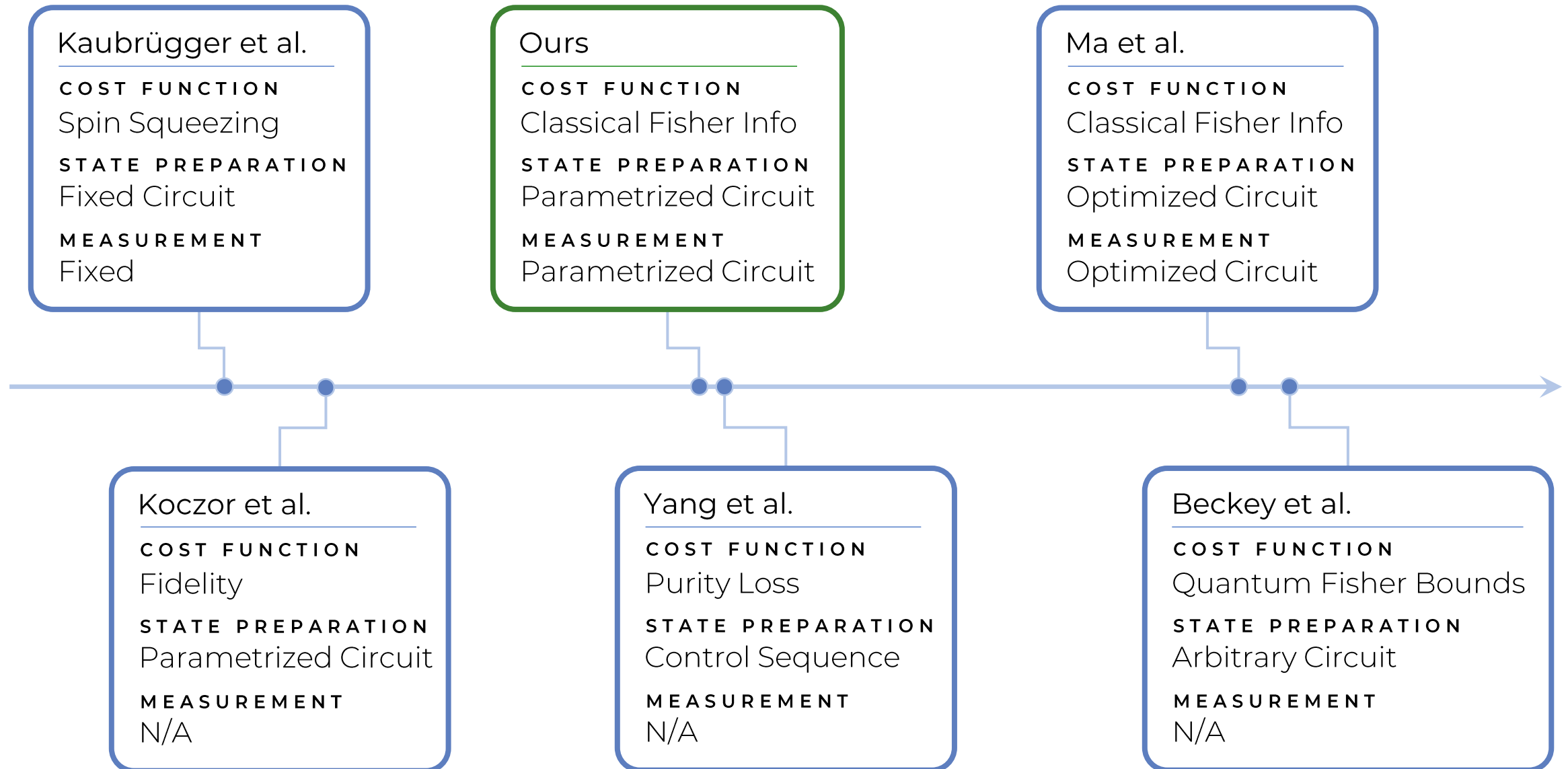
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Take-Home Message

Variational methods can be used to improve quantum sensors

Thank you for your attention!



Paper



Demo



Slides